

A large, vibrant astronomical image of a nebula, likely the Ring Nebula, showing intricate patterns of glowing gas in shades of blue, white, and yellow against a dark background. The image is positioned in the upper half of the slide, partially overlapping the header.

# LARGE-SCALE OPTIMAL POWER FLOW WITH NO GUARANTEE ON FEASIBILITY

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## 4 General framework

- | iTesla, large-scale OPF models with no guarantee on feasibility, type of model (intensity limits, phase-shifting transformers)
- | Numerical experiments on real data from European TSOs

## 4 Problems encountered by solving a direct approach

- | Difficulties to converge
- | Not possible to know the status of the solution and characteristics of the network state

## 4 Proposed solution: a progressive filtering process

- | The direct approach is replaced by a multi-step solution process
- | Each step amounts to solving an easier problem

## 4 Computational experiments

# GENERAL FRAMEWORK

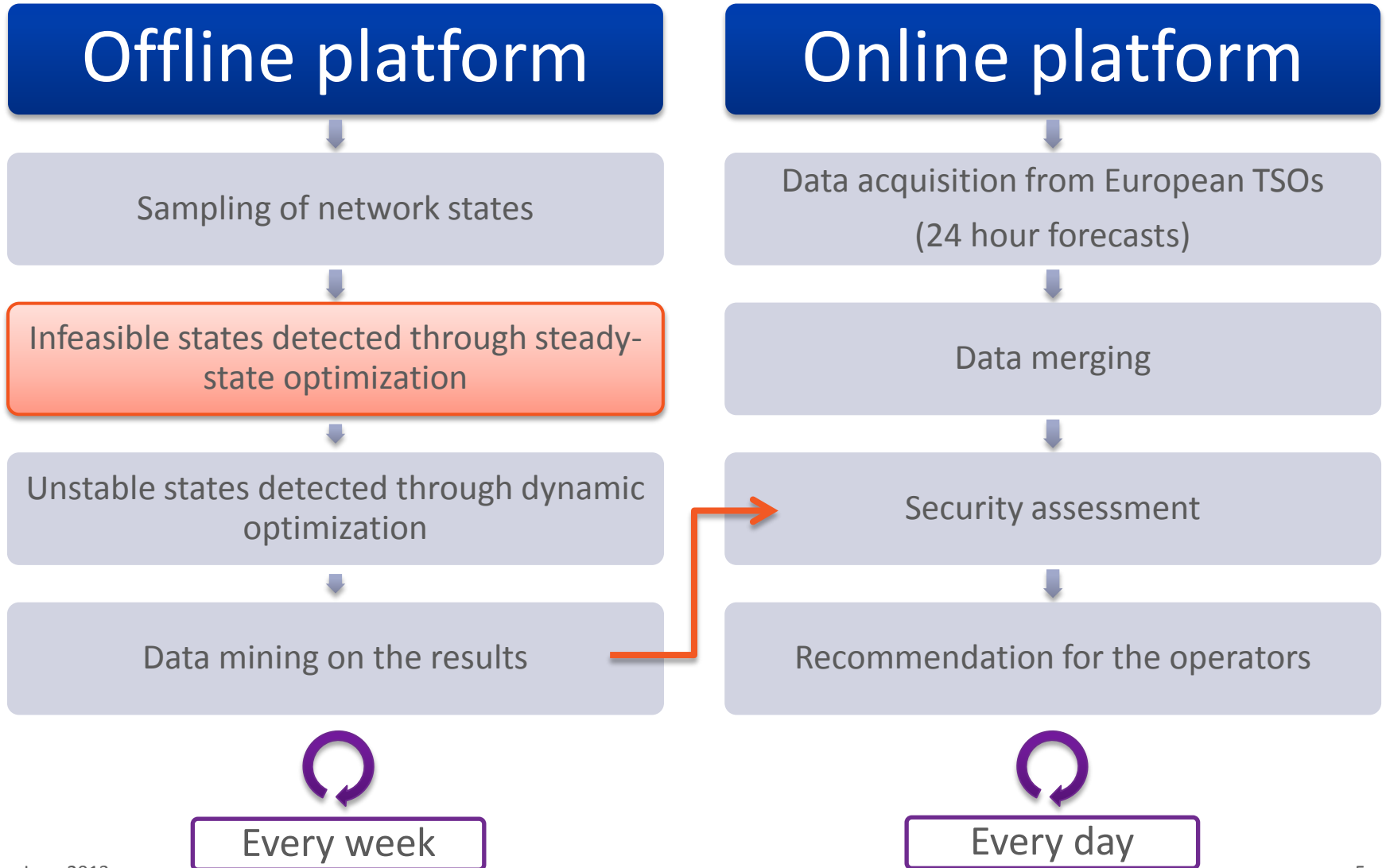
4 iTesla is a pan-European R&D project that aims at assessing the security of a large scale power network by means of security rules computed offline

- | Coordinated by RTE (Réseau de Transport d'Electricité)
- | Includes 6 European TSOs and 13 R&D companies
- | Official website: <http://www.itesla-project.eu/>

4 Two major platforms developed

1. **Offline**: explore the network state space to draw the separation between stable and unstable states (using data mining techniques)
2. **Online**: evaluate computed security rules on the current network situation and provide recommendations to TSOs





## ▣ Here we focus on the offline task

- | Monte Carlo simulations provide us with many network states (~10,000)
- | We want to filter out the ones that are **not feasible**

## ▣ The mathematical model is a modified AC-OPF

- | Polar PQV formulation
- | Limits on voltage magnitudes
- | Maximum intensity levels on lines (nonlinear inequality constraints)
- | Limits on production levels
- | Kirchhoff law at each node (nonlinear equality constraints)

- 4 **When necessary**, fixed injection can be modified
  - | Positive fixed injection at a node can be decreased
    - **Production curtailment** of fatal production unit (**PC**)
  - | Negative fixed injection at a node can be increased
    - **Load shedding** (**LS**)
  
- 4 Use of specific absolute tolerance on each constraint
  - | Limits on voltage magnitude
  - | Maximum limit on intensity level
  - | Balance of active and reactive power at each node
  - | Limits on active and reactive level of production units

- ▣ Network data comes from real data (recollection of network data from several European TSOs)
  - | > 7000 nodes
  - | > 8000 lines
  - | ~ 700 production units
  
- ▣ This leads to a large scale nonlinear optimization problem
  - | The input data has not been verified
  - | We have no guarantee that a feasible solution actually exists
  
- ▣ The dataset is composed of 843 test cases which correspond to a whole week of real data from European TSOs



- ▣ The goal is to answer the following questions
  - | Is the OPF model feasible without **PC** or **LS**?
  - | Can the OPF model be made feasible with only **PC**?
  - | Can the OPF model be made with both **PC** and **LS**?
- ▣ If no **LS** is needed, **PC** is used as little as possible
- ▣ If needed, **LS** is used as little as possible, even if this leads to use more **PC**

# DIRECT APPROACH

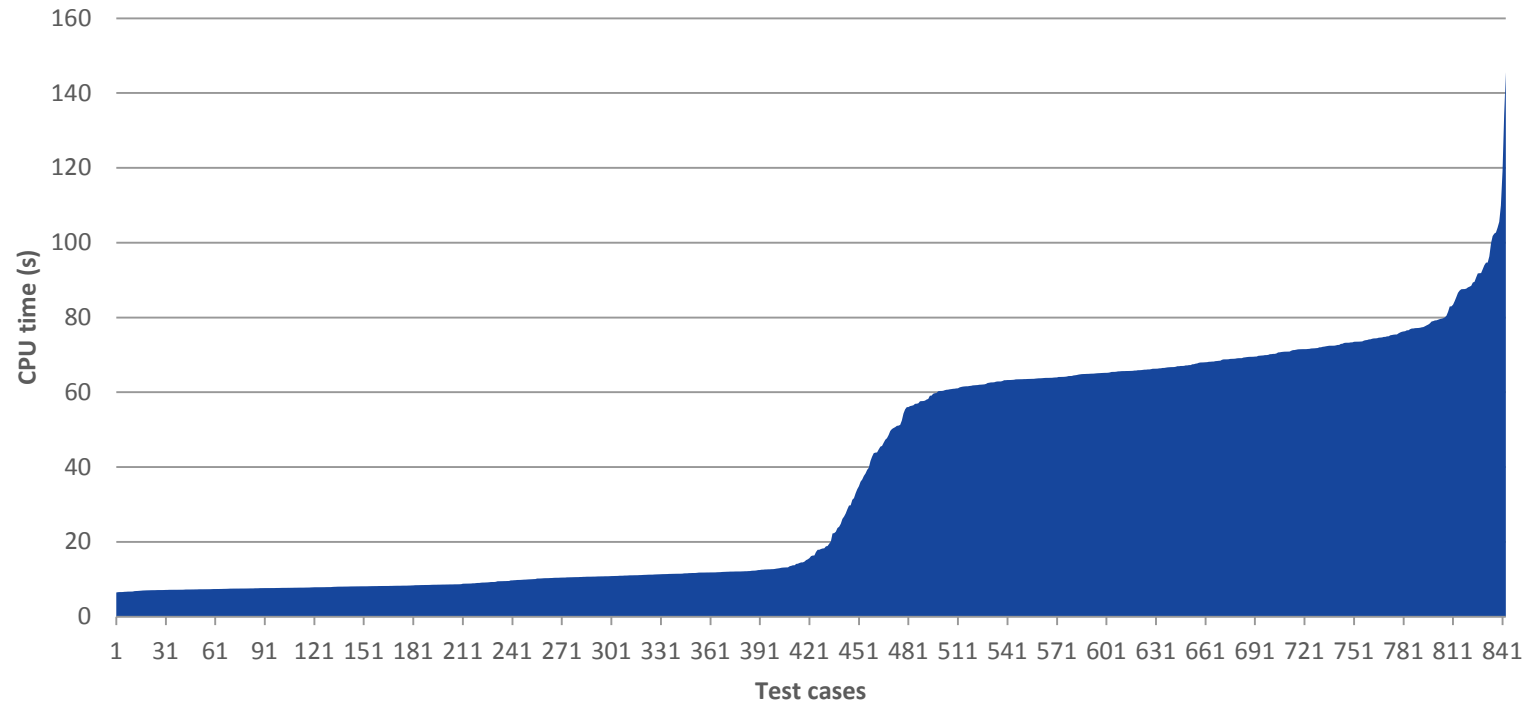
- 4 The objective is to minimize load shedding and production curtailment on each node

  - |  $\min LS + 0.1 \cdot PC$
  - | Reminding that:
    - If no *LS* is needed, *PC* is used as little as possible
    - If needed, *LS* is used as little as possible, even if this leads to use more *PC*
- 4 The problem is solved directly using

  - | KNITRO 8.1.1, a state-of-the-art nonlinear optimization solver
  - | AMPL, a standard modeling language for mathematical optimization
- 4 KNITRO uses an interior-point method to solve the OPF

  - | Newton-Raphson + line search descent, projected conjugate gradient, etc.
  - | The number of interior-point iterations is limited to 200

## Direct approach



Out of 843 test cases

| 360 test cases reached the iteration limit

The feasibility assessment is based on the last solution iterate

- ⚠ When the maximal number of iterations is reached, no conclusion can be made on the test case
  - | The solution point may be infeasible while the test case actually is feasible
  - | The solution point may be feasible with positive *PC* or *LS*, while a solution with no *PC* or *LS* actually exists (and we would like to find it)
- ⚠ If the test case is found infeasible within the iteration limit, the origin of the infeasibility remains unclear

# PROGRESSIVE FILTERING APPROACH

4 A progressive filtering approach has been developed to achieve the following goals:

| **gain stability in terms of convergence** and CPU usage

| **obtain more detailed information on the reasons why a network state is infeasible:**

- Can we make it feasible by curtailing some production at specific network nodes?
- Is it necessary to perform load shedding as well?
- In which nodes should the power injection be modified?

- 4 The maximum limits on intensity levels make the problem much harder to solve

  - | Main reason: they act as a capacity constraint on line power flows
  - | All models solve within 10 seconds without such limits
    - Production targets and demands are usually well balanced
  
- 4 Relaxing the power balance constraints tends to decrease the power flow needed on lines

  - | This tends to decrease the current intensity level :  $|I|^2 = \frac{|S|^2}{|V|^2}$
  
- 4 Thus, slack variables are applied to active and reactive power balances only, as it is sufficient to make the model feasible

  - |  $slack_P$  on active power balances
  - |  $slack_Q$  on reactive power balances



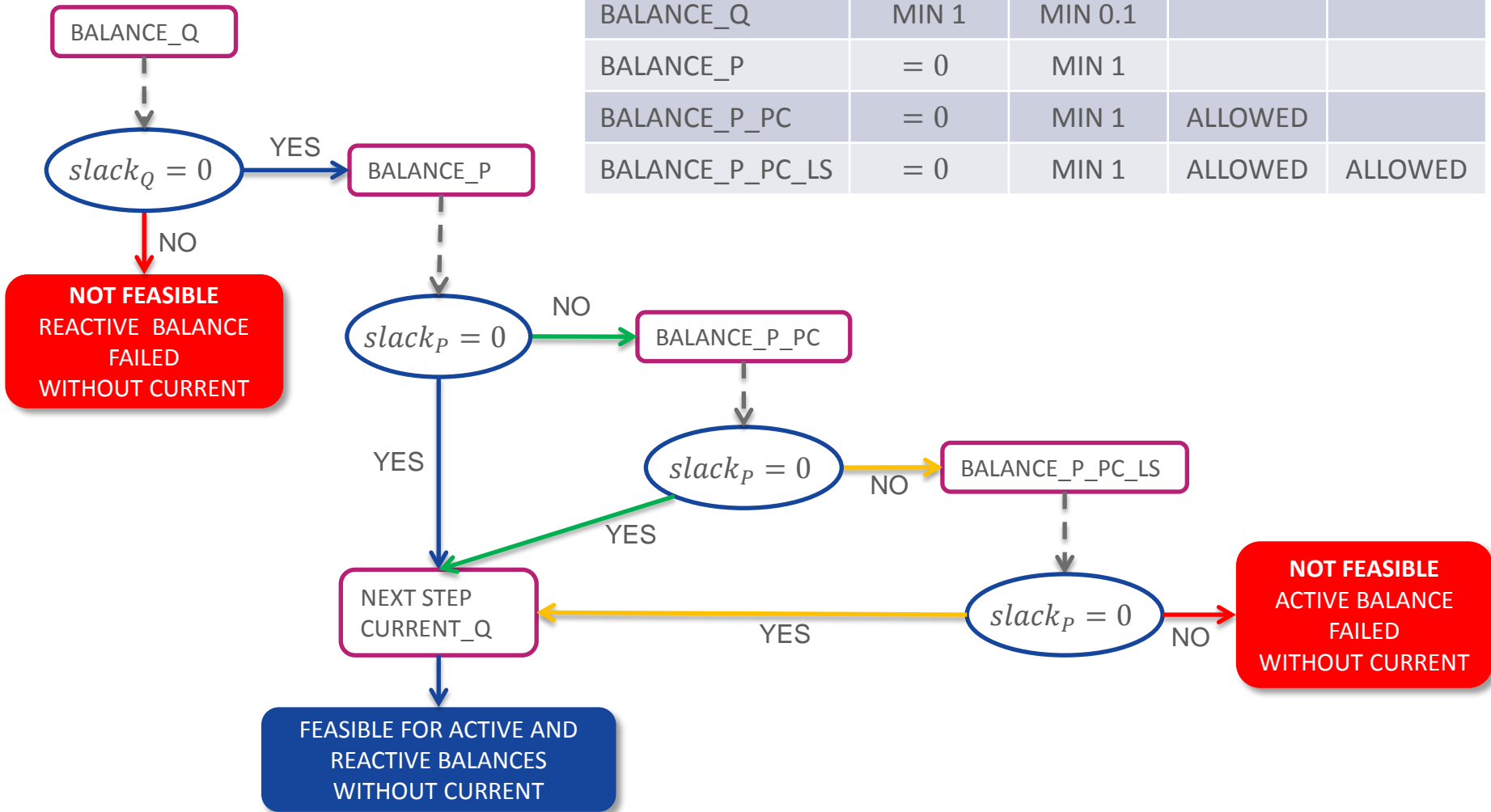
- 4 The progressive filtering approach is applied twice

  - | without current intensity levels
  - | with current intensity levels
- 4 Each step of the filtering procedure has a dedicated objective function and may or may not use slack variables
- 4 Each problem must be solved within less than 100 iterations
- 4 The localization of **PC** or **LS** is only perform when the maximum limits on intensity level are enforced

  - | Intensity limits have a great impact of the location of **PC** and **LS**

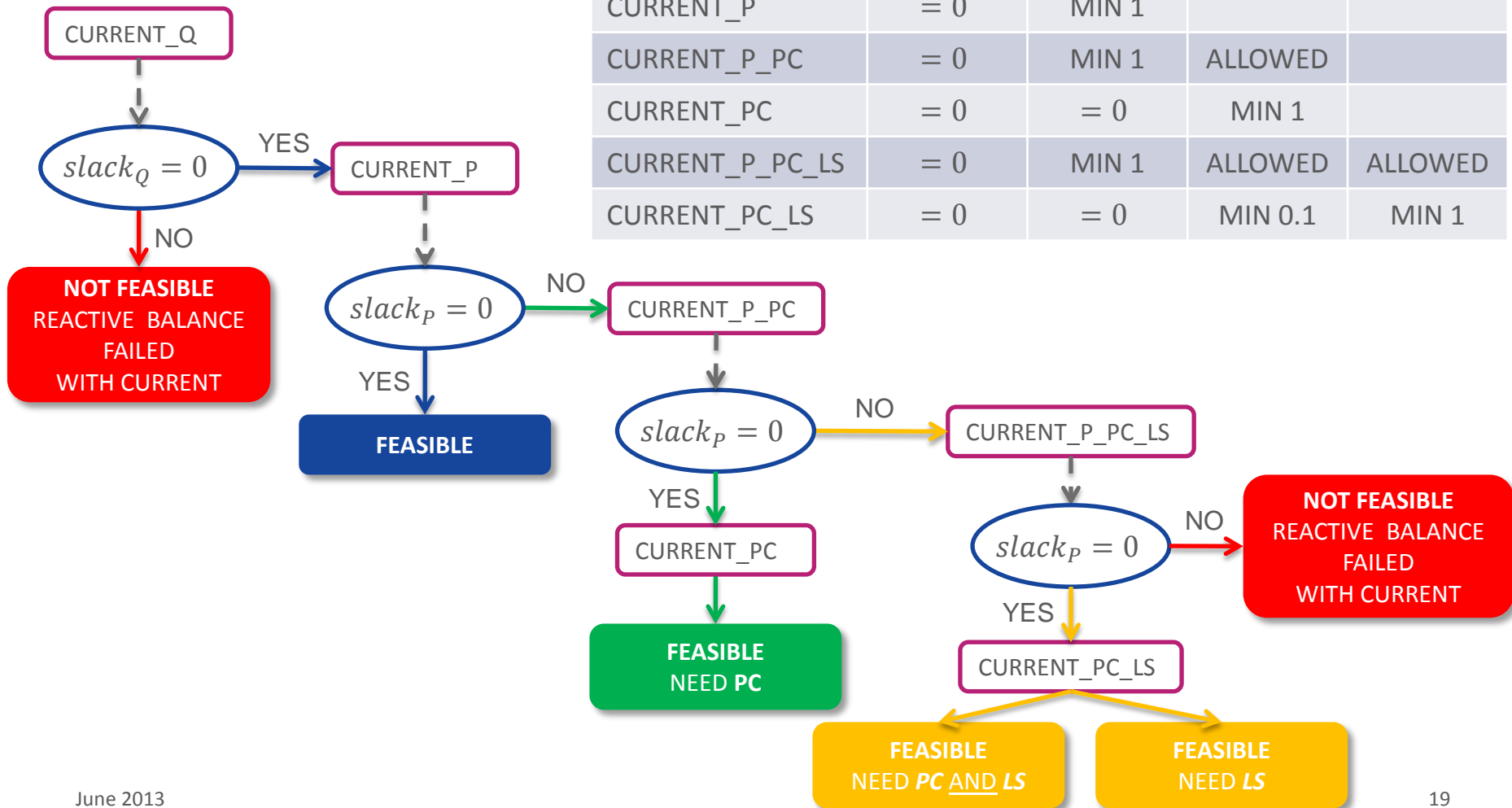
# STEPS WITHOUT INTENSITY LIMIT

STEP	$slack_Q$	$slack_P$	PC	LS
BALANCE_Q	MIN 1	MIN 0.1		
BALANCE_P	= 0	MIN 1		
BALANCE_P_PC	= 0	MIN 1	ALLOWED	
BALANCE_P_PC_LS	= 0	MIN 1	ALLOWED	ALLOWED

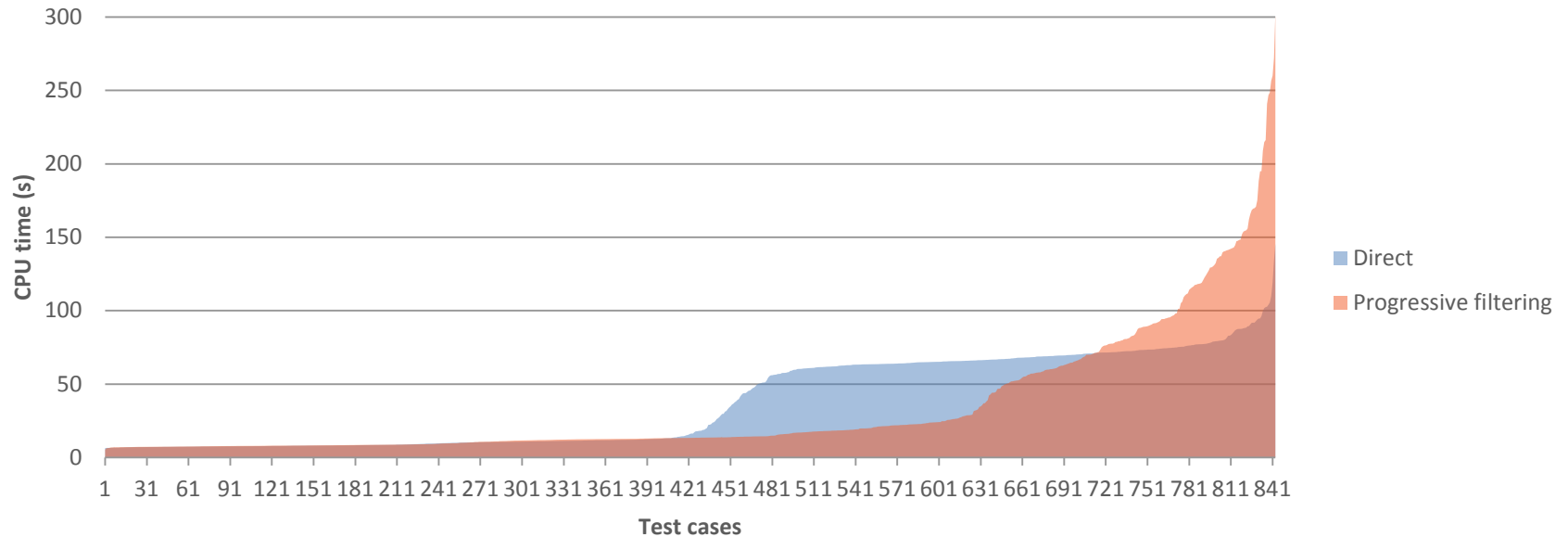


# STEPS WITH INTENSITY LIMIT

STEP	$slack_Q$	$slack_P$	PC	LS
CURRENT_Q	MIN 1	MIN 0.1		
CURRENT_P	= 0	MIN 1		
CURRENT_P_PC	= 0	MIN 1	ALLOWED	
CURRENT_PC	= 0	= 0	MIN 1	
CURRENT_P_PC_LS	= 0	MIN 1	ALLOWED	ALLOWED
CURRENT_PC_LS	= 0	= 0	MIN 0.1	MIN 1



## Direct vs. Progressive filtering approach



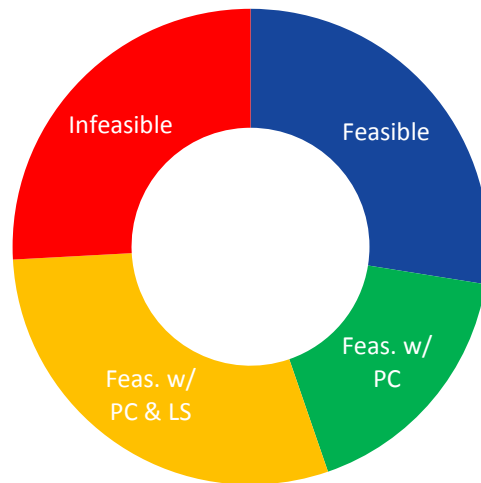
About 50 minutes of total CPU time is saved over the 843 test cases

- Direct approach: 8 hours 47 minutes
- Progressive filtering approach: 7 hours 58 minutes

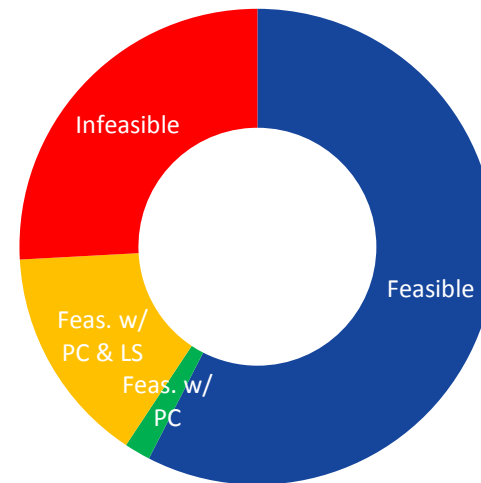
However, some test cases (not feasible without *PC* or *LS*) are solved with high CPU times

- More time is spent in order to recover detailed infeasibility information

**Direct approach  
Solution status**



**Progressive filtering  
Solution status**



| The direct approach missed:

- 253 instances that are found feasible without **PC**
- 123 instances that are found feasible with or without **PC**

| The progressive approach provides more information on infeasibilities:

- issues with active/reactive power balance, issues with intensity limits
- localization of such difficulties

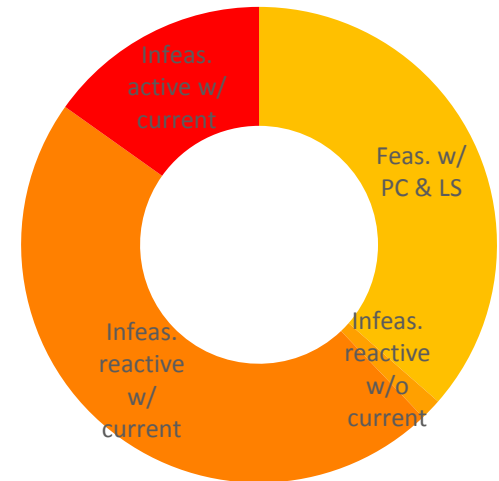
## Reasons for infeasibilities:

- About 1/3 of infeasible models can be made feasible by using **LS**
- About 1/2 of infeasibilities are due to reactive power balance issues
- About 1/6 of infeasibilities are due to active power balance issues

## The average CPU time per step is

- 4.5 seconds for power balance slack minimization without intensity limits
- 13.5 seconds for power balance slack minimization with intensity limits
- 32.0 seconds for **PC** minimization (when used)
- 44.4 seconds for **LS** minimization (when used)

## Progressive filtering Solution status



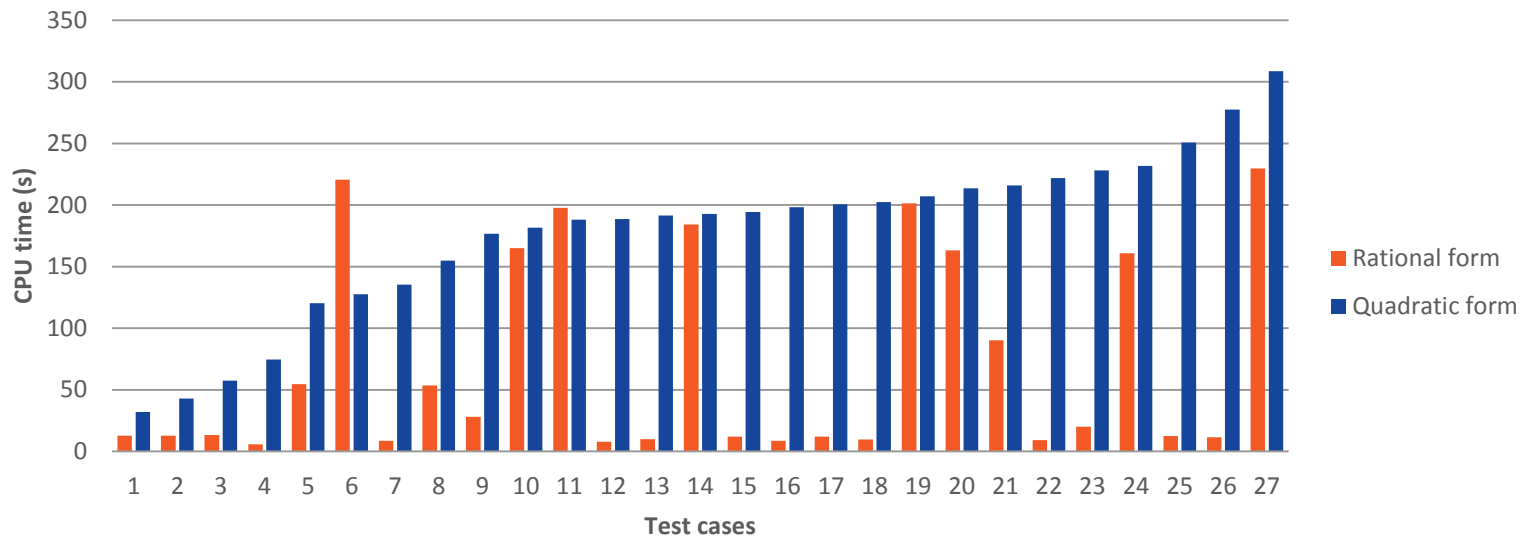
# ON THE INTENSITY LIMIT

4 The maximum intensity level constraint can be expressed in a quadratic form or in a rational form

|  $|I|^2 \leq \bar{I}^2$  or  $\sqrt{|I|^2} \leq \bar{I}$

- | The rational formulation scales better and leads to better performance
  - Demonstrated by an experiment on a reduced dataset of 27 test cases

**Rational vs. quadratic intensity formulation**





# CONCLUSION

- 4 A progressive filtering procedure has been developed in order to detect infeasibilities for large-scale OPF problems
- 4 The procedure is tested on a whole week of real data from European TSOs (843 test cases)
  - | The filtering process is able to solve more instances than the direct approach
- 4 The KNITRO performance was greatly improved by
  - | scaling the model
  - | using constraint-specific feasibility tolerances
    - avoids unnecessary long convergence runs to achieve default tolerances
    - new feature that will be available in the next KNITRO release

A large, vibrant blue background with a horizontal band of colorful light trails (red, orange, yellow, green, cyan) across the top. Below this band, the background is a deep blue with a faint, ethereal image of a nebula or galaxy, showing bright, wispy structures in white and light blue.

THANK YOU FOR YOUR ATTENTION

ANY QUESTIONS?

